

# CLAIMS

1. A method for detecting a crater end of a continuously cast product, the method comprising the steps of installing  
5 an ultrasonic shear wave sensor for transmitting an ultrasonic shear wave to the continuously cast product and receiving the transmitted ultrasonic shear wave and an ultrasonic longitudinal wave sensor for transmitting an ultrasonic longitudinal wave to the continuously cast  
10 product and receiving the transmitted ultrasonic longitudinal wave at the same position in a continuous casting machine or at two positions apart from each other in a casting direction but at the same position in a transverse direction of the cast product, detecting based on variations  
15 of an ultrasonic signal received by the ultrasonic shear wave sensor that the crater end of the cast product is matched with the installed position of the ultrasonic shear wave sensor, calibrating a calculation formula for determining the crater end from a propagation time of an  
20 ultrasonic longitudinal wave signal such that the crater end computed from the propagation time of the ultrasonic longitudinal wave signal at that time is matched with the installed position of the ultrasonic shear wave sensor, and after the calibration, determining the crater end from the  
25 propagation time of the ultrasonic longitudinal wave signal

based on the calibrated calculation formula.

2. The method for detecting a crater end of a continuously cast product according to Claim 1, further comprising the steps of installing a second ultrasonic shear wave sensor downstream of said ultrasonic shear wave sensor in the casting direction at the same position in the transverse direction of the cast product, detecting based on variations of an ultrasonic signal received by the second ultrasonic shear wave sensor that the crater end of the cast product is matched with the installed position of the second ultrasonic shear wave sensor, and further calibrating the calculation formula for determining the crater end from the propagation time of the ultrasonic longitudinal wave signal such that the crater end computed from the propagation time of the ultrasonic longitudinal wave signal at that time is matched with the installed position of the second ultrasonic shear wave sensor.

3. The method for detecting a crater end of a continuously cast product according to Claim 1 or 2, wherein the calculation formula for determining the crater end from the propagation time of the ultrasonic longitudinal wave signal differs between when the crater end is positioned upstream of the installed position of the ultrasonic

longitudinal wave sensor in the casting direction and when the crater end is positioned downstream thereof.

4. A method for detecting a crater end of a continuously  
5 cast product, the method comprising the steps of installing  
an ultrasonic shear wave sensor for transmitting an  
ultrasonic shear wave to the continuously cast product and  
receiving the transmitted ultrasonic shear wave in a  
continuous casting machine, detecting based on variations of  
10 an ultrasonic signal received by the ultrasonic shear wave  
sensor that the crater end of the cast product is matched  
with the installed position of the ultrasonic shear wave  
sensor, calibrating a physical property value used in  
calculation based on a heat condition equation such that the  
15 crater end computed based on the heat condition equation  
using casting conditions at that time is matched with the  
installed position of the ultrasonic shear wave sensor, and  
after the calibration, determining the crater end by the  
calculation based on the heat condition equation under  
20 respective casting conditions by using the calibrated  
physical property value.

5. A method for detecting a crater end of a continuously  
cast product, the method comprising the steps of installing  
25 an ultrasonic shear wave sensor for transmitting an

ultrasonic shear wave to the continuously cast product and receiving the transmitted ultrasonic shear wave in a continuous casting machine, detecting based on variations of an ultrasonic signal received by the ultrasonic shear wave sensor that the crater end of the cast product is matched with the installed position of the ultrasonic shear wave sensor, calibrating a physical property value used in calculation based on a heat condition equation such that the crater end computed based on the heat condition equation using casting conditions at that time is matched with the installed position of the ultrasonic shear wave sensor, determining the crater ends by the calculation based on the heat condition equation by using the calibrated physical property value and measuring the propagation times by the ultrasonic shear wave sensor under various casting conditions, obtaining a relationship between the crater ends computed based on the heat condition equation and the propagation times measured by the ultrasonic shear wave sensor, and determining the crater end from the propagation time measured by the ultrasonic shear wave sensor based on the obtained relationship.

6. A method for detecting a crater end of a continuously cast product, the method comprising the steps of installing, in a continuous casting machine, a first ultrasonic shear

wave sensor for transmitting an ultrasonic shear wave to the continuously cast product and receiving the transmitted ultrasonic shear wave and at least one of an ultrasonic longitudinal wave sensor for transmitting an ultrasonic longitudinal wave to the continuously cast product and receiving the transmitted ultrasonic longitudinal wave and a second ultrasonic shear wave sensor for transmitting an ultrasonic shear wave and receiving the transmitted ultrasonic shear wave, detecting based on variations of an ultrasonic signal received by the first ultrasonic shear wave sensor that the crater end of the cast product is matched with the installed position of the first ultrasonic shear wave sensor, calibrating a physical property value used in calculation based on a heat condition equation such that the crater end computed based on the heat condition equation using casting conditions at that time is matched with the installed position of the first ultrasonic shear wave sensor, determining the crater ends by the calculation based on the heat condition equation by using the calibrated physical property value and measuring the propagation times by the ultrasonic longitudinal wave sensor or the second ultrasonic shear wave sensor under various casting conditions, obtaining a relationship between the crater ends computed based on the heat condition equation and the propagation times measured by the ultrasonic longitudinal

wave sensor or the second ultrasonic shear wave sensor, and  
determining the crater end from the propagation time  
measured by the ultrasonic longitudinal wave sensor or the  
second ultrasonic shear wave sensor based on the obtained  
5 relationship.

7. A method for detecting a crater end of a continuously  
cast product, the method comprising the step of, from a  
propagation time of an ultrasonic longitudinal wave signal  
10 measured by an ultrasonic longitudinal wave sensor installed  
in the continuous casting machine for which the calibration  
has been made or in a different continuous casting machine,  
determining the crater end in the relevant continuous  
casting machine by using the calculation formula calibrated  
15 by the method according to any one of Claims 1 to 3.

8. A method for detecting a crater end of a continuously  
cast product, the method comprising the steps of executing  
the calculation based on the heat condition equation by  
20 using the physical property value calibrated by the method  
according to Claim 4 and the casting conditions of the  
continuous casting machine for which the calibration has  
been made or of a different continuous casting machine, and  
determining the crater end in the relevant continuous  
25 casting machine.

9. A method for detecting a crater end of a continuously cast product, the method comprising the step of, based on the relationship between the crater ends computed based on the heat condition equation and the propagation times measured by the ultrasonic sensor, which is obtained by the method according to Claim 5 or 6, determining the crater end in a target continuous casting machine from a propagation time of an ultrasonic signal measured by an ultrasonic shear wave sensor or an ultrasonic longitudinal wave sensor installed in the continuous casting machine for which said relationship has been obtained or in a different continuous casting machine.

10. A method for detecting a crater end of a continuously cast product, the method comprising the steps of determining the crater end of the cast product by the method for detecting a crater end of a continuously cast product according to any one of Claims 1 to 6, and adjusting a casting speed or intensity of secondary cooling for the cast product in accordance with the determination result.

11. An apparatus for detecting a crater end of a continuously cast product, the apparatus comprising an ultrasonic shear wave sensor made up of an ultrasonic shear

wave transmitter for transmitting an ultrasonic shear wave to the continuously cast product and an ultrasonic shear wave receiver for receiving the transmitted ultrasonic shear wave, an ultrasonic longitudinal wave sensor made up of an  
5 ultrasonic longitudinal wave transmitter for transmitting an ultrasonic longitudinal wave to the continuously cast product and an ultrasonic longitudinal wave receiver for receiving the transmitted ultrasonic longitudinal wave, the ultrasonic longitudinal wave sensor being installed at the  
10 same position in a continuous casting machine as the ultrasonic shear wave sensor or a position apart from the ultrasonic shear wave sensor in a casting direction but at the same position in a transverse direction of the cast product, and a crater end computing unit for determining the  
15 crater end of the cast product by using a calculation formula in accordance with an ultrasonic signal received by the ultrasonic longitudinal wave sensor, wherein at the time when it is confirmed based on variations of an ultrasonic signal received by the ultrasonic shear wave sensor that the  
20 installed position of the ultrasonic shear wave sensor and the crater end of the cast product are matched with each other, the calculation formula is calibrated such that the crater end computed based on the calculation formula is matched with the installed position of the ultrasonic shear  
25 wave sensor.



12. The apparatus for detecting a crater end of a continuously cast product according to Claim 11, further comprising a second ultrasonic shear wave sensor installed  
5 downstream of said ultrasonic shear wave sensor in the casting direction at the same position in the transverse direction of the cast product, wherein at the time when it is confirmed based on variations of an ultrasonic signal received by the second ultrasonic shear wave sensor that the  
10 installed position of the second ultrasonic shear wave sensor and the crater end of the cast product are matched with each other, the calculation formula is further calibrated such that the crater end computed based on the calculation formula is matched with the installed position  
15 of the second ultrasonic shear wave sensor.

13. The apparatus for detecting a crater end of a continuously cast product according to Claim 11 or 12, wherein the ultrasonic shear wave transmitter and the  
20 ultrasonic longitudinal wave transmitter are installed on one side of the cast product, the ultrasonic shear wave receiver and the ultrasonic longitudinal wave receiver are installed on the other side of the cast product, and a set of the ultrasonic shear wave transmitter and the ultrasonic  
25 longitudinal wave transmitter and a set of the ultrasonic

shear wave receiver and the ultrasonic longitudinal wave receiver are each constituted as an integral electromagnetic ultrasonic sensor having three or more magnetic poles in the transverse direction of the cast product and made up of a longitudinal wave coil arranged to wind the surrounding of an inner magnetic pole aside from a surface thereof and a shear wave coil arranged to overlie the magnetic pole surface.

10      14. An apparatus for detecting a crater end of a continuously cast product, the apparatus comprising an ultrasonic shear wave sensor made up of an ultrasonic shear wave transmitter for transmitting an ultrasonic shear wave to the continuously cast product and an ultrasonic shear wave receiver for receiving the transmitted ultrasonic shear wave, and a heat condition equation unit for executing calculation based on a heat condition equation in accordance with casting conditions and values of physical properties, thereby determining the crater end of the cast product, wherein at the time when it is confirmed based on variations of an ultrasonic signal received by the ultrasonic shear wave sensor that the installed position of the ultrasonic shear wave sensor and the crater end of the cast product are matched with each other, at least one of the values of physical properties used in the calculation based on the

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heat condition equation is calibrated such that the crater end computed by the heat condition equation unit is matched with the installed position of the ultrasonic shear wave sensor.

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15. An apparatus for detecting a crater end of a continuously cast product, the apparatus comprising an ultrasonic shear wave sensor made up of an ultrasonic shear wave transmitter for transmitting an ultrasonic shear wave  
10 to the continuously cast product and an ultrasonic shear wave receiver for receiving the transmitted ultrasonic shear wave, a heat condition equation unit for executing calculation based on a heat condition equation in accordance with casting conditions and values of physical properties,  
15 thereby determining the crater end of the cast product, and a crater end estimating unit for estimating the crater end of the cast product based on a relationship between an ultrasonic signal received by the ultrasonic shear wave sensor and the crater end computed by the heat condition  
20 equation unit, wherein at the time when it is confirmed based on variations of the ultrasonic signal received by the ultrasonic shear wave sensor that the installed position of the ultrasonic shear wave sensor and the crater end of the cast product are matched with each other, at least one of  
25 the values of physical properties used in the calculation

based on the heat condition equation is calibrated such that the crater end computed by the heat condition equation unit is matched with the installed position of the ultrasonic shear wave sensor, wherein after the calibration of the physical property value, the crater end estimating unit obtains a relationship between the ultrasonic signal received by the ultrasonic shear wave sensor and the crater end computed by the heat condition equation unit, and wherein the crater end is determined from a propagation time measured by the ultrasonic shear wave sensor based on the obtained relationship.

16. An apparatus for detecting a crater end of a continuously cast product, the apparatus comprising an ultrasonic shear wave sensor made up of an ultrasonic shear wave transmitter for transmitting an ultrasonic shear wave to the continuously cast product and an ultrasonic shear wave receiver for receiving the transmitted ultrasonic shear wave, an ultrasonic longitudinal wave sensor made up of an ultrasonic longitudinal wave transmitter for transmitting an ultrasonic longitudinal wave to the continuously cast product and an ultrasonic longitudinal wave receiver for receiving the transmitted ultrasonic longitudinal wave, a heat condition equation unit for executing calculation based on a heat condition equation in accordance with casting

conditions and values of physical properties, thereby  
determining the crater end of the cast product, and a crater  
end estimating unit for estimating the crater end of the  
cast product based on a relationship between an ultrasonic  
5 signal received by the ultrasonic shear wave sensor and the  
crater end computed by the heat condition equation unit,  
wherein at the time when it is confirmed based on variations  
of the ultrasonic signal received by the ultrasonic shear  
wave sensor that the installed position of the ultrasonic  
10 shear wave sensor and the crater end of the cast product are  
matched with each other, at least one of the values of  
physical properties used in the calculation based on the  
heat condition equation is calibrated such that the crater  
end computed by the heat condition equation unit is matched  
15 with the installed position of the ultrasonic shear wave  
sensor, wherein after the calibration of the physical  
property value, the crater end estimating unit obtains a  
relationship between an ultrasonic signal received by the  
ultrasonic longitudinal wave sensor and the crater end  
20 computed by the heat condition equation unit, and wherein  
the crater end is determined from a propagation time  
measured by the ultrasonic longitudinal wave sensor based on  
the obtained relationship.